

# Analyzing Physics-Informed Neural Networks for Solving Classical Flow Problems

Rishabh Puri<sup>a</sup>, Mario Rüttgers<sup>ab</sup>, Rakesh Sarma<sup>a</sup>, Andreas Lintermann<sup>a</sup>

<sup>a</sup> Jülich Supercomputing Center, Forschungszentrum Jülich

<sup>b</sup> Institute of Aerodynamics and Chair of Fluid Mechanics (AIA), RWTH Aachen University

## Physics-Informed Neural Networks for Computational Fluid Dynamics (CFD)

- Predictions by purely data-driven Deep Neural Networks (DNNs) can suffer from physical inconsistencies
- Physics-Informed Neural Networks (PINNs) integrate physical laws, governing equations, initial and/or boundary conditions into the loss function to improve the predictive capability of DNNs<sup>1</sup>
- Though PINNs can be trained on limited spatial or temporal data to attain accurate results, data-free PINNs are difficult to train<sup>2</sup>
- Based on the complexity of the problem and the desired accuracy of the solution, hybrid models combining CFD solvers and PINNs have been developed<sup>3</sup>

### Problem description and governing equations

The current study juxtaposes PINN-generated flow fields to analytical solutions and compares the predictive capability of PINNs with that of DNNs, which do not have a physical loss as a constraint. The following cases are considered in the current study,

#### • Poiseuille flow<sup>4</sup>

Pressure drop along pipe length

$$\frac{\partial p}{\partial x} = \mu \left( \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} \right), \frac{\partial p}{\partial r} = 0, -\frac{dp}{dx} = \frac{\Delta p}{L_p} = G_p, u(r) = \frac{G_p}{4\mu} (R_p^2 - r^2)$$

#### • Potential flow

$$\nabla \times \vec{u} = 0, \nabla \cdot \vec{u} = 0, \text{ where flow velocity, } \vec{u} = \nabla \phi \text{ — Potential function}$$

Cylinder

$$\phi = Ux + \frac{Q}{\pi} \cdot \frac{x}{x^2 + y^2}$$

Rankine oval

$$\phi = Ux + \frac{m}{4\pi} \cdot \log \left[ \frac{(x+a)^2 + y^2}{(x-a)^2 + y^2} \right]$$

#### • Blasius boundary layer flow<sup>5</sup>

$$\frac{\partial \rho u}{\partial x} + \frac{\partial \rho v}{\partial y} = 0$$

$$\rho u \frac{\partial u}{\partial x} + \rho v \frac{\partial u}{\partial y} = \frac{\partial}{\partial y} \left( \mu \frac{\partial u}{\partial y} \right)$$

$$\frac{\partial p}{\partial x} = 0, \frac{\partial p}{\partial y} = 0$$

Scaled stream function and the modified ODE

$$\eta \sim \frac{y}{\delta(x)} = \frac{y}{(vx/U_0)^{1/2}}, f(\eta) = \frac{\psi}{(vxU_0)^{1/2}}$$

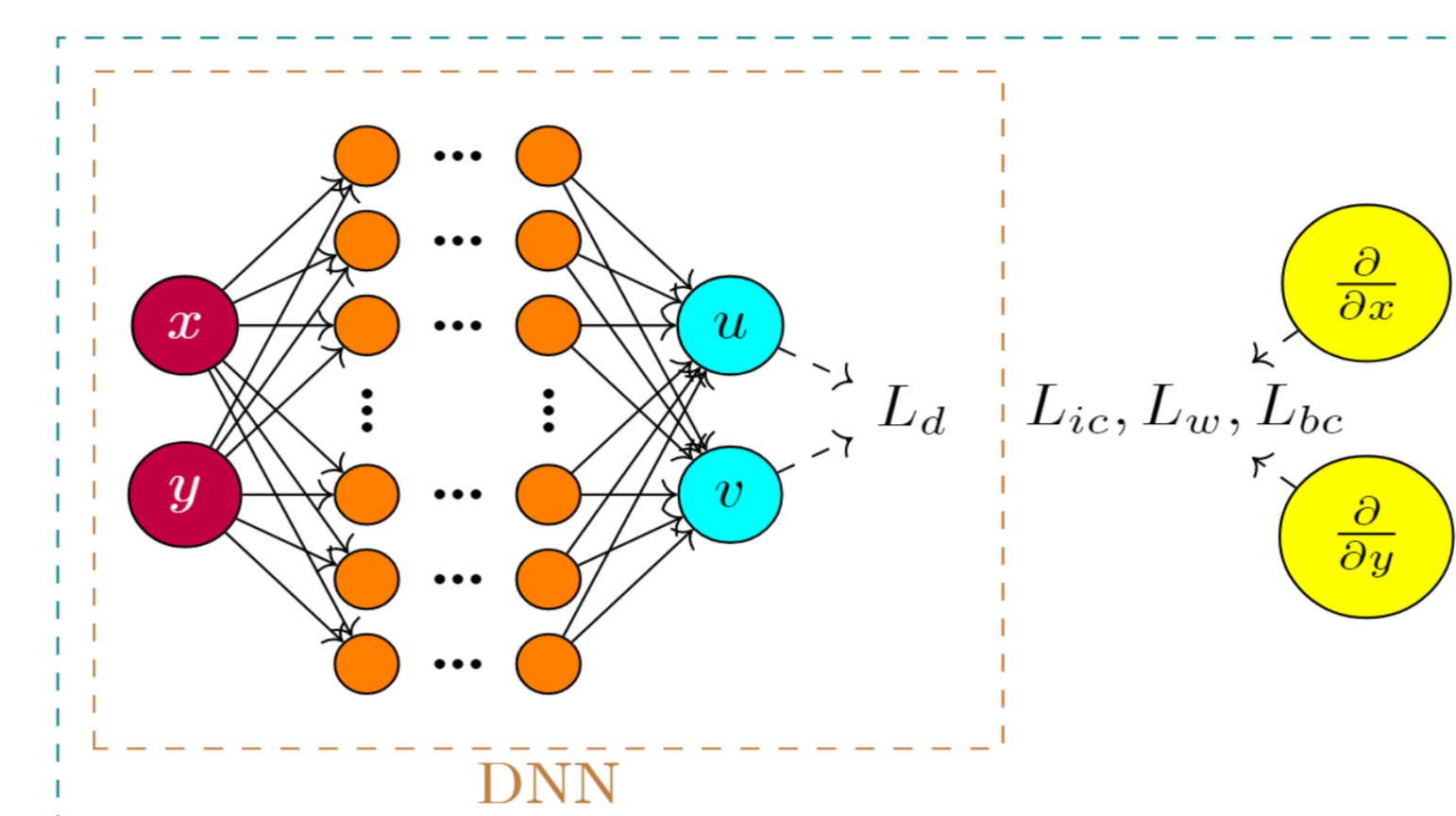
$$\frac{d^3 f}{d\eta^3} + \frac{1}{2} f \frac{d^2 f}{d\eta^2} = 0, f(\eta=0) = 0,$$

$$f'(\eta=0) = 0, f'(\eta \rightarrow \infty) = 1$$

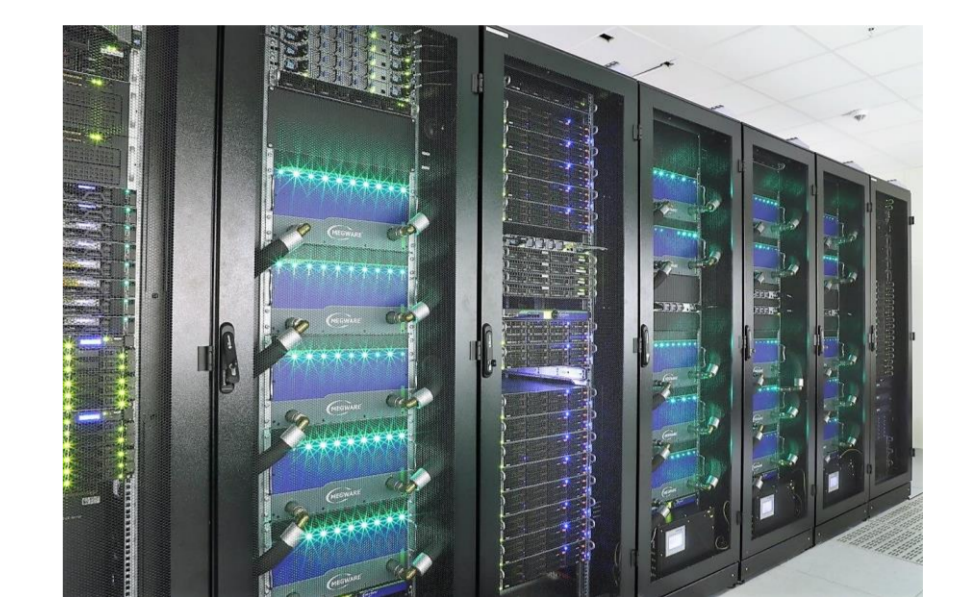
PINNs are computationally expensive compared to DNNs and the achieved accuracy must justify additional computation costs.

### Workflow

#### • Network architecture for Potential flow



#### • HPC systems



DEEP-EST-ESB



JURECA-DC

#### • Input and Output parameters

Flow case	Input	Output
Poiseuille flow	$r$	$u$
Potential flow	$x, y$	$u, v$
Blasius equation	$\eta$	$f', f''$

#### • Loss function

$$L = L_d + L_g$$

$$L_d = \frac{1}{N_d} \sum_{n=1}^{N_d} |\theta - \theta^*|^2, L_g = \frac{1}{N_g} \sum_{n=1}^{N_g} |g(\theta)|^2, \theta \rightarrow u, v, f', f''$$

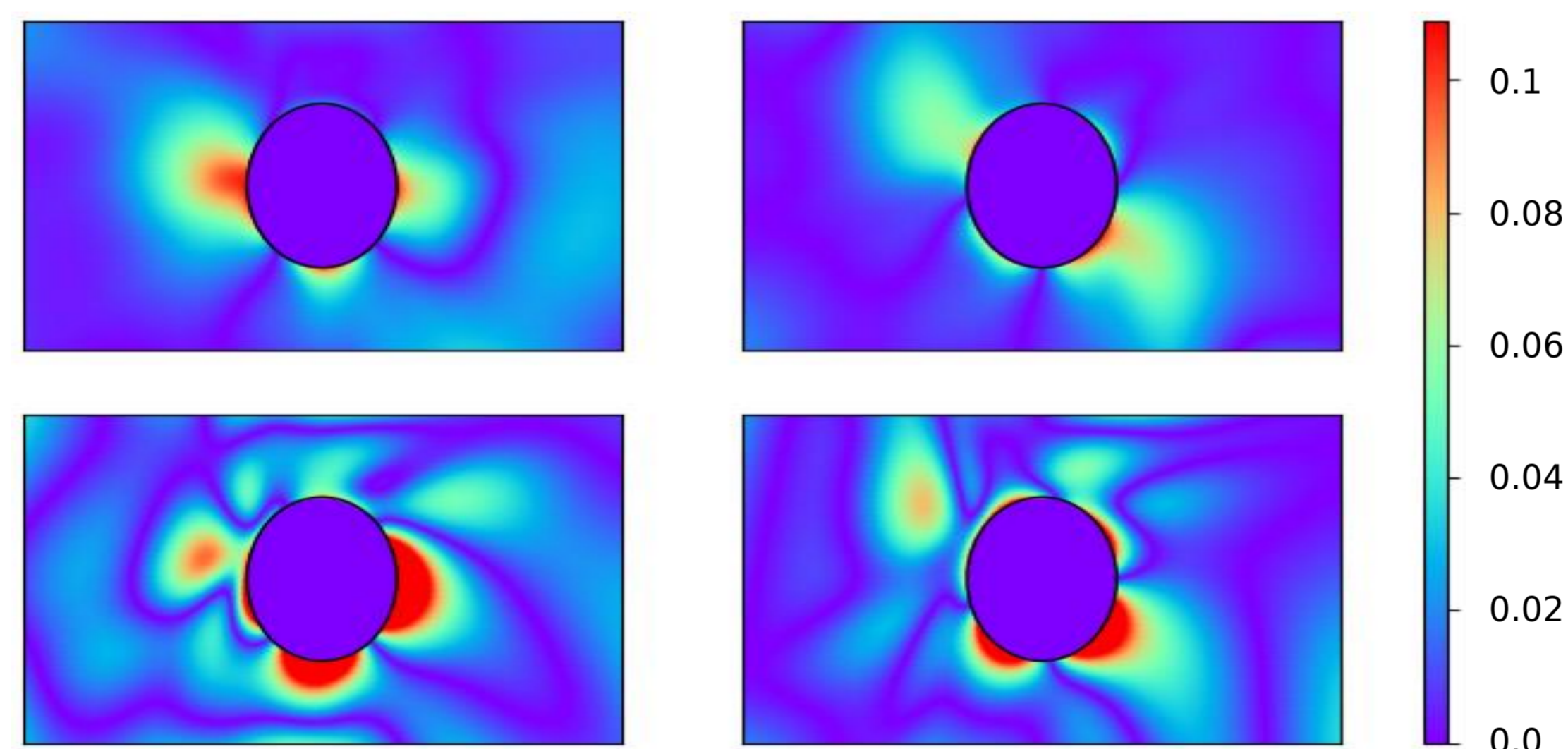
MSE loss from prediction

Loss from governing equations on ic, w, bc data

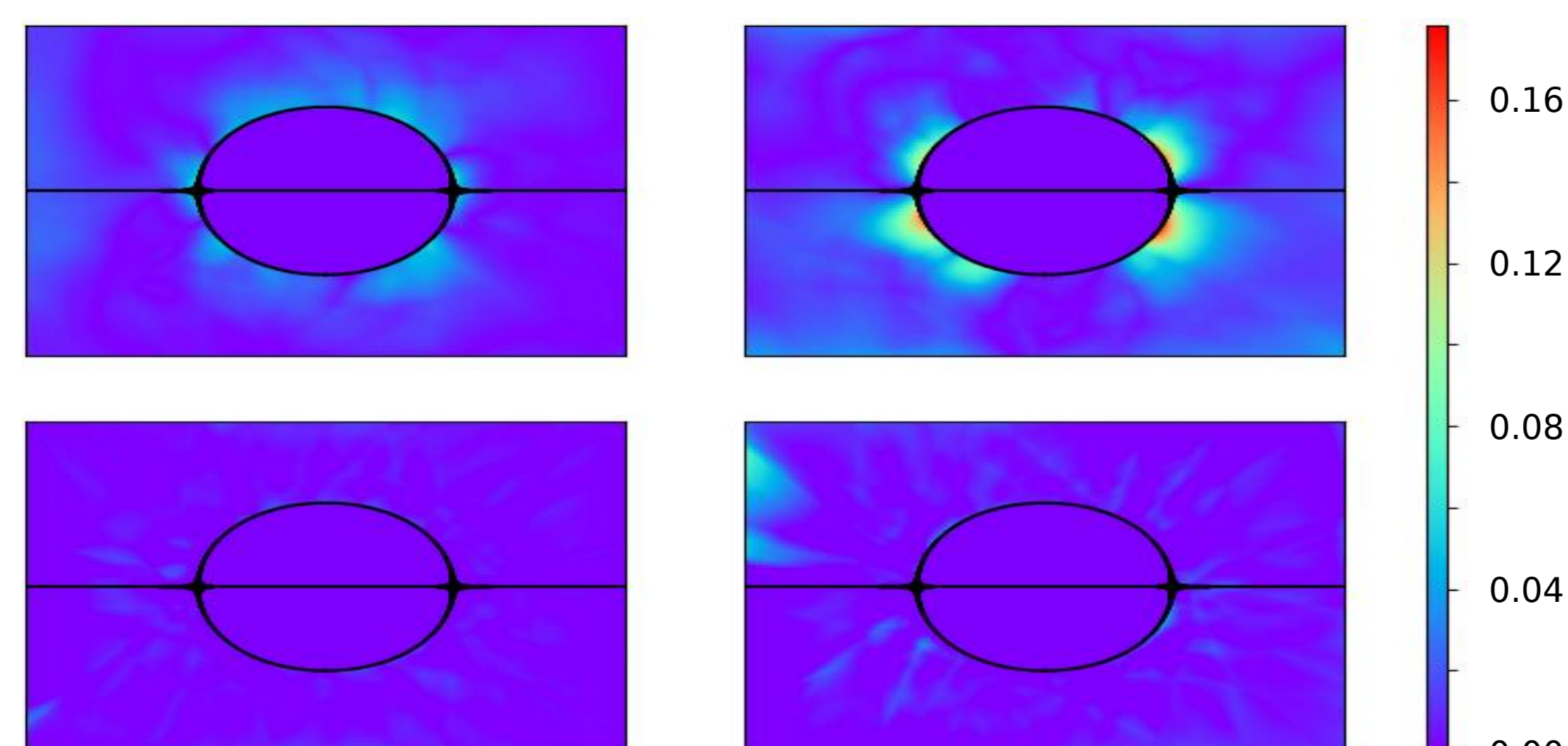
ic, initial conditions  
w, wall or body boundary condition  
bc, boundary conditions

## Results

#### • Prediction Error density<sup>#</sup>



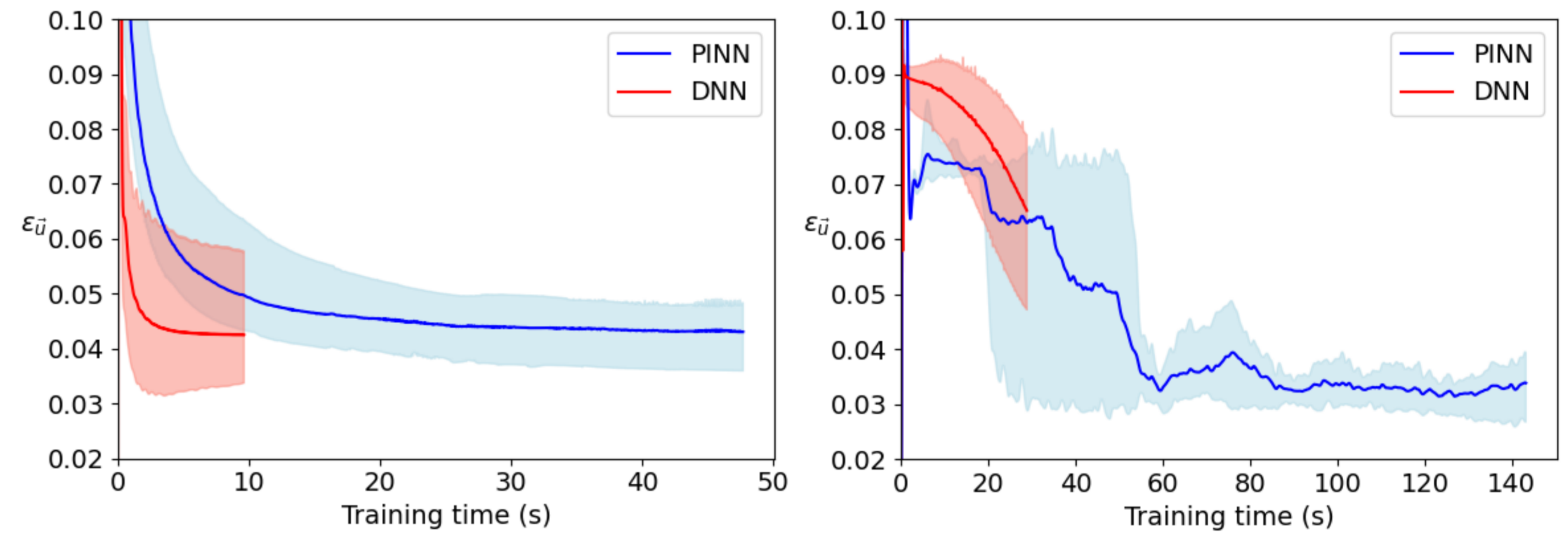
Potential flow - Cylinder



Potential flow - Rankine oval

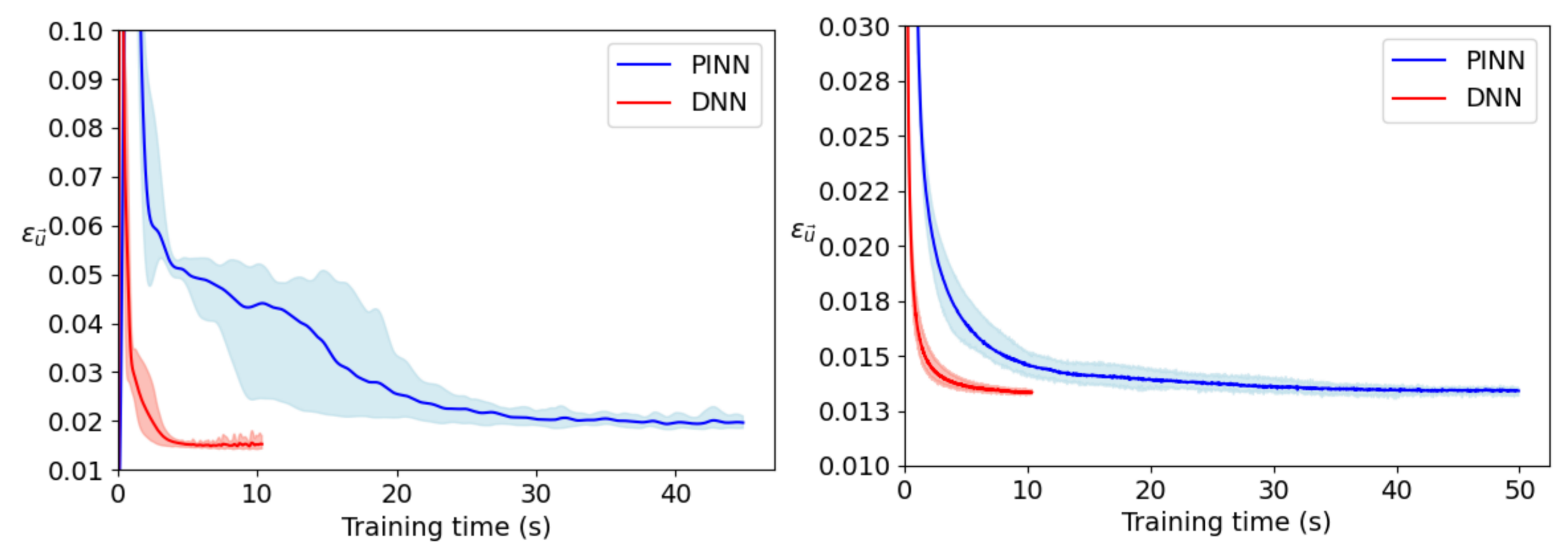
<sup>#</sup> Columns: Velocity fields  $u$  (left) and  $v$  (right); Rows: PINN (top) and DNN (bottom)

#### • Testing error



Poiseuille flow

Potential flow Cylinder



Potential flow Rankine oval

Blasius boundary layer flow

## Conclusion

- The inclusion of physical constraints in NNs improves the prediction capability of the network implemented for the cases of Poiseuille flow, potential flow around a cylinder, and Blasius boundary layer flow, especially in the near wall flow field
- For the case of potential flow around the Rankine oval, the normalization of the flow data is affected by extreme gradients near the source and sink and the PINN struggles to predict the flow field accurately

## Future work

- The prediction capability of PINNs will be evaluated for further types of governing equations, i.e., a lattice-Boltzmann method, and for more complex flow problems, i.e., 2D Taylor-Green vortex
- The effect of constant parameters like the pressure gradient in one-dimensional flow problems will be studied to improve the calculation of the physical loss

## References

1. Karniadakis, G. E.; Kevrekidis, I. G.; Lu, L.; Perdikaris, P.; Wang, S. and Yang, L. (2021) Physics-informed machine learning. *Nature Reviews Physics* 3, 6 (01 Jun 2021), 422–440
2. Chuang, P. and Barba, L. A. (2022) Experience report of physics informed neural networks in fluid simulations: pitfalls and frustrations
3. Illarramendi, E.; Alguacil, A.; Bauerheim, M.; Misdariis, A.; Benedicte, C. and Benazera, E. (2020) Towards a hybrid computational strategy based on Deep Learning for incompressible flows
4. Stokes, G. G. (1845). "On the theories of the internal friction of fluids in motion, and of the equilibrium and motion of elastic solids". *Transactions of the Cambridge Philosophical Society*. 8: 287–341
5. Prandtl, L. (1904). Über Flüssigkeitsbewegung bei sehr kleiner Reibung. In *Chronik des III. Internationalen Mathematiker-Kongresses in Heidelberg*, Adolf Krazer (Ed.). ACM Press, Heidelberg, 484–491

## Acknowledgement

The research leading to these results has been conducted in the CoE RAISE project, which receives funding from the European Union's Horizon 2020 – Research and Innovation Framework Programme H2020-INFRAEDI-2019-1 under grant agreement no. 951733.